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Improving sub-surface image with conventional wisdom & innovative approach – Case study from Krishna-Godavari Basin, India

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Summary

The Krishna-Godavari Basin, in the East coast of India is a passive margin basin which belongs to a unique poly cyclic extensional province. Geologically the basin exhibits a very complex sub-surface picture, especially in the west Godavari sub-basin area. The sub-surface imaging becomes a challenge because of the thick basaltic layer at the shallow level in this part of the basin. Many 2-D and 3-D seismic campaigns were conducted in this area. But the sub surface could not be mapped satisfactorily including the basement. The acquisition efforts were hampered further because of the logistic problems due to presence of large water bodies, aqua culture and dense population. A systematic approach was made to study the problems associated with data acquisition and suggest optimum parameters for undertaking a large carpet 3-D campaign. The studies included modeling, synthetic data generation & processing and other studies drawn from the collective wisdom of experienced campaigners & domain experts. Efforts were made to compute the foldage required, from the study of vintage data. The integrated study resulted in optimizing the parameters like far offset requirement, type of shooting geometry, foldage etc. to facilitate better imaging of the subsurface.

Innovative recovery programs were made with the help of software tools and detailed survey data to plan acquisition over the logistically challenged areas. The data acquisition campaign was carried out successfully as per plan by deploying 6 parties over an area of 1500 Sq.Km. The efforts culminated with the best in class sub-surface image in one of the most challenging on-land portions. This is evident from the comparison of vintage data with the data extracted from the 3-D volume.

Introduction

Krishna-Godavari Basin: The K-G Basin in the East coast of India, is a passive margin basin which belongs to a unique poly cyclic extensional province. It is analogous to geological set up of Continental margin of Black Ridge in Arctic ocean and Beaufort Sea of Atlantic Ocean. The basin evolved over the eastern Ghat tectonic grain in consequence of Indo-Antarctica plate separation and the influence of oblique extension during Jurassic period. The Basin consists of two parts—the peri-cratonic passive margin superimposed on the orthogonal Pranhita Godavari basin.

The origin of the basin is related to three stages of rifting. The Proterozoic Proto-rift (NW-SE) accommodated the Purana group of sediments. Thereafter the Gondwana rifting followed and superimposed on the Proterozoic graben and accommodated the Gondwana group of sediments. The final

rifting (NE-SW) took place during the breakup of the Gondwana land and was followed by drifting of the separated part of the Gondwana land. The drifting was also accompanied by south easterly tilting of the basin. This tilt is clearly manifested by the monoclinal dip of the basaltic flow towards the basin. The basaltic flow (Razole formation) is further affected by a fault system called the Matsyapuri- Palakollu fault which divides the basin into two distinct regimes for exploration as well as the on-shore & off-shore part of the basin. (The target for exploration to the north of this fault are the pre-trappeans (Cretaceous and older) and to the south of it are the Post – trappeans (Paleogene & Neogene).)





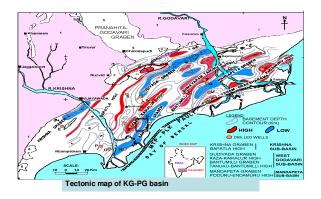


Figure 1: Tectonic map of KG-PG Basin. The Box indicates the location of the study area.

Basin configuration: The basin is marked by three grabens – Krishna sub basin, West Godavari sub-basin and East Godavari sub – basin, separated by two horsts – Bapatla high & Bhimavaram-Tanuku high (Fig-1). The West Godavari sub-basin is further sub divided into Gudivada garben & Bantumilli graben separated by Kaza-Kaikalur high. The basin displays a dispersed hydrocarbon habitat containing hydrocarbons at different stratigraphic levels ranging from oldest Mandapeta Sand to the Youngest Godavari clay in the off-shore.

Imaging challenge

Geologically the basin exhibits a very complex sub-surface picture, especially in the West Godavari sub-basin area. The sub-surface imaging becomes a challenge because of the thick basaltic layer at the shallow level in this part of the basin. The basaltic layer varies in thickness from 50 m to 160 m with depth of 500 m to 1500 m in this part of the basin. Further the area is infested with aqua and agricultural farms and water bodies which pose severe logistic challenge for the acquisition efforts. This results in in-adequate sampling of the sub-surface.

A no.of prospects have been identified in the West Godavari sub-basin on the basis of available seismic data and the drilled wells. No. of 2-D & few 3-D campaigns were undertaken for extending the prospects. Because of poor imaging of the sub-surface, proper delineation of the prospects could not be done. Clear & unique picture of the sub-surface, comprising of the basement, basement related

faults, thin lenticular sands within the older sediments below the basalts etc. could not be mapped unambiguously so far. A list of the seismic campaigns done so far is listed in Annexure -1.



Figure 2: Areas identified for carpet 3-D

In this block, four areas were identified for detailed and satisfactory mapping. It was decided to acquire a carpet 3-D with seamless integration of the areas (Fig, 2). It became important to adopt a systematic approach to understand the sub-surface, optimize the acquisition parameters and use proper geometry to improve the data.

Analysis of older campaigns: A thorough analysis of the earlier campaigns (Annexure-1) indicated that there were problems related to multiples, identification of basement and other horizons, clarity of the tectonic features and the structural aspects. The main reasons for the seismic imaging failure were identified as,

- Improper / In-adequate offset selection
- Poor signal to noise ratio
- Less than adequate foldage
- Logistic challenges
- Poor recovery planning for logistic gaps

Once the reasons were identified it was decided to find solutions using a systematic approach.

Methodology

A. Modeling studies: A systematic modeling study was undertaken. Models were prepared along dip & strike





directions (Fig 3). For various geometries ray tracing was done and synthetic data was generated. The synthetic data was processed and analyzed. The studies indicated that there were no shadow zones or illumination problems associated with basalts and reasonably good image of the sub-surface upto basement could be obtained (Fig 4).

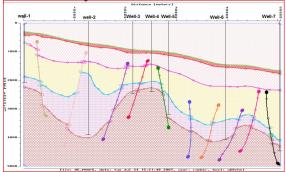


Figure 3: The digital model generated in computer using the geological model

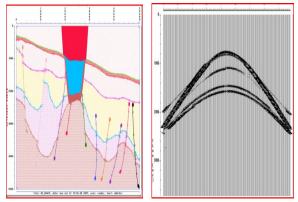


Figure 4: Synthetic shot record for sym.split spread , 5500m Offset

B. Far offset selection: One of the important parameters for data acquisition was the proper far offset for mapping the basement / deepest reflector. It was seen that the earlier investigations were woefully short of the proper far offset. With the help of modeling studies, well data and available seismic data the

maximum offset needed for 30 % NMO stretch criteria was computed (Table No. 1).

Depth	V int	Vrms	2-T	Xnmo
(m)	(m/s)	(m/s)	(Seconds)	(m)
0	2000	2000	0.00	0
53	2500	2480	0.05	72
1467	3750	2533	1.18	1643
1544	3000	2597	1.23	1743
1814	2800	2603	1.41	2004
1874	3000	2674	1.45	2121
2313	3500	2875	1.74	2741
3166	3750	2954	2.23	3606
3527	3900	3051	2.42	4045
3990	3700	3073	2.66	4475
4150	5000	3341	2.74	5023

Table-1 Computed travel times, Vrms & far offset for 30 $\%\,$ stretch mute

- C. Improving S/N ratio: The S/N ratio had been a serious concern in this area because of the basalts and logistic problems. Because of the sharp velocity contrast at the top of the basalt, most of the impinging energy is reflected back, making the transmitted energy weaker, which is further weakened at the other interfaces. More complications are brought in because of absorption & scattering within the basalt, refraction along the basalt top, multiples between the basalt & the low velocity near surface layers and interference between direct arrivals & the reflected arrivals from deeper zones at far offsets. Because of the dense population and intense human activities, the ambient noise conditions were very high. Since explosives are the best option as source, it was decided to use proper charge size & depth on the basis of experiments.
- D. Optimum foldage: It was realized that one of the reasons for the poor data quality was the low foldage, to offset the lack of adequate S/N ratio. So it was important to determine the optimum foldage required. Many authors have suggested ways to compute the optimum foldage requirement from the field data. A methodlogy based on correlation functions to compute





S/N ratio and the foldage (*Mike Galbraith, Seismic Image Software*) was used as follows:

 $AC/XC = (S^2+N^2) / S^2$ Re-arranging we get:

S/N = 1 / sqrt((AC/XC) - 1) where AC,XC were the correctation co-efficients, S & N were signal & noise .

The field records for various campaigns were studied. The auto-correlation & cross-correlation coefficients were computed. The S/N ratio for the raw data was calculated for various campaigns for different values of detectability % in terms of the acoustic contrast (fig 5).

From these Foldage can be computed as,

Foldrequired = $(S/N_{required}/S/N_{raw})^2$

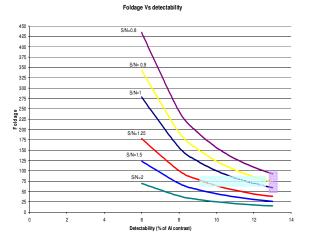


Figure 5: Foldage Vs Detectability for different S/N ratio ranges for optimizing foldage parameter

E. Logistic challenges: The biggest factor in this area of operation was the logistic problems posed by the rich agri & aqua cultural tracts and huge water bodies.. These are inaccessible areas where laying of receivers could not be done as per plan and taking shots was impossible. This resulted in data gaps & poor / insufficient sub-surface sampling of data. So it was necessary to prepare proper recovery plans to adequately cover these areas.

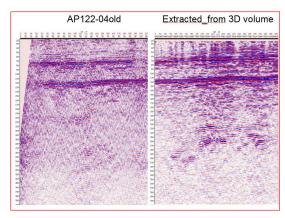


Figure 6: Comparison of vintage data with the recently acquired 3-D data

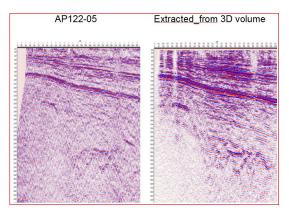


Figure 7: Comparison of vintage data with the recently acquired 3-D data





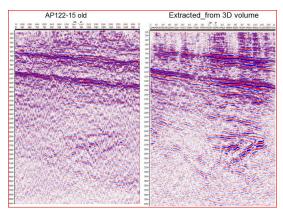


Figure 8: Comparison of vintage data with the recently acquired 3-D data

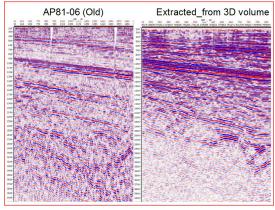


Figure 9: Comparison of vintage data with the recently acquired 3-D data $\,$

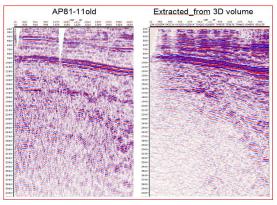


Figure 10: Comparison of vintage data with the recently acquired 3-D data $\,$

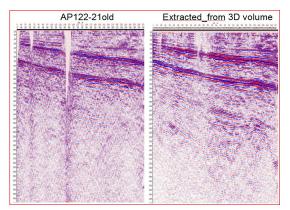


Figure 11: Comparison of vintage data with the recently acquired 3-D data





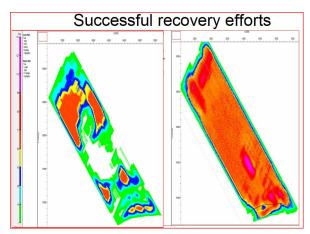


Figure 12: Foldage improvement before and after recovery management

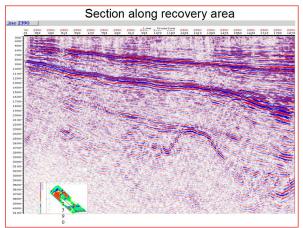


Figure 13: Section along the recovered portion shown above.

Observations & Discussion

Based on theoretical considerations and the modeling studies, asymmetric split spread type of geometry with a maximum offset of 5500 m was chosen. The most crucial parameter was to decide the optimum foldage required. The study of vintage data indicated that the S/N ratio varied from 0.8 to 2.0 in the study area. The detectability, which could be expressed as a percentage of Acoustic Impedance was found to vary from 9 to 13 % for the fulfillment of the G & G objectives. Based on the chart in Figure 4, the

foldage required under various ambient noise conditions was varying from 48 to 96 for achieving the above detectability. So it was decided to go for a coverage of 8000 % which would be optimum under various field conditions, to provide the proper sub-surface imaging. The higher foldage might also provide the proper cushion for any loss of foldage due to tough logistic conditions. Other field parameters were optimized based on the field tests. Logistic challenges were addressed by suitable recovery plans based on the survey data. The planned recovery programs resulted in near recovery of the necessary offsets which otherwise would have been lost (Figure12,13). During processing suitable noise elimination programs were used for reducing the effect of cultural noise. Harmonization of offsets, amplitudes and foldages further improved the data quality.

Conclusions

The systematic approach to design the proper 3-D acquisition geometry based on the industry standard principles helped in finalizing the critical parameters. For the first time the optimum foldage required, was computed based on the methods suggested by experts, in this part of the basin. A scientific recovery management was undertaken using the proper software, which resulted in good coverage of the areas (Figures 12-13), which otherwise would have been data gaps. The result was a dramatic improvement in the quality of the data acquired. The subsurface image provided a clear picture of the basement configuration for the entire 3-D carpet area (Figures 6-11). It is hoped that new prospects and leads can be obtained from this data.

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Annexure- 1

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YEAR / PA	RTY	AREA		GI	SI	NEAR OFFSET	FAR OFFSE	FIEI LAY	LD YOUT	FOLDAG		
89-90 / GP-	11	KAIK'LR- BANTUMII	J	30	30	150	3000	ENI	O-ON	96 / 48		
86 / GP-11		KAIKALUR			25	300	2675	ENI	O-ON	96 / 48		
92-93/ GP1	1	KAIKALURU		25	25	150	2525	ENI	O-ON	96 / 48		
95-96 / GP-	04	KAZA- NIM'KURU	K	30	30	180	3030	ENI	D-ON	96 / 48		
91-92 / GP-	04	TANUKU- PALAKOLU		30	30	180	3030	ENI	O-ON	96 / 48		
91-92/ GP-1	.2	E OF BHIMAVAI		35	35	175	3500	ENI	O-ON	96 / 48	7	
91-92/ GP-2	28	W OF BHIMAVAI		35	35	175	3500	ENI	O-ON	96 / 48		
92-93 / GP-	04	SW OF BANTUMII		35	35	175	3500	ENI	O-ON	96 / 48	- 53	
93-94 / GP-	11	NSP- LANKAPALEM		25	25	300	2675	ENI	O-ON	96 / 48		
94-95 / GP-	04	NANDIGAMA		30	30	180	3030	ENI	O-ON	96 / 48		
94-95 / GP-	11	GAJALAPUDU		30	30	180	3030	ENI	O-ON	96 / 48		
94-95 / GP-	12	BHIMAVARAM		35	35	175	3500	ENI	D-ON	96 / 48		
95-96 / GP-	04	KAZA- NIMAKURU		30	30	180	3030	ENI	O-ON	96 / 48		
96-97 / GP-	04	MAHADEVPA BANTUMILI		30	30	180	3030	ENI	O-ON	96 / 48		
98-99 / GP-	11	BANTUMII LAXMIPUR	.I-	35	35	175	3500	ENI	O-ON	96 / 48		
99-2000 GP	-11	KESNAPAL SUKNETUR	.I-	35	35	175	3500	ENI	O-ON	96 / 48		
2002-03 / G	P-11	BHIMAVAI PENAMAN	RAM-	30	30	180	3030	ENI	O-ON	96 / 48		
2003-04 GP-11		BANTUMII	BANTUMILI- PADATADAKA		30	180	3750	ENI	O-ON	120 / 60	Ī	
2004-05 / G	P-11			20	40	120	5220	ENI	O-ON	256 / 64		
i i			Detail	s of ge	ophysic	al campaig	ns (3-D)	4			Ь	
EAR / PARTY	AREA		GI	SI	BIN	GEOM	ETRY	FOLD	RLI	SLI	CHANNE	
-96 / GP-28	KAIK		40	80	SIZE 20X4	PARAI	IEI	14X3	240	320	336	
	LING.	ALA-PH I				SWAT	H		0.000000	(5.53)	7.7.70	
-97 / GP-28		ALA-PH II		80	20X40	SWAT	H	14X3	240	320	336	
-98 / GP-28		IK'LR- 40 GALA-PH III		80	20X40	PARAI SWAT		14X3	240	320	336	
00-01 / GP-12	SURY	ARAOPETA	50	50	25X2	ORTHO BRICK		6X5	300	450	540	

Table 2: Details of previous geophysical campaigns in the area

BRICK





Annexure- 1I

3-D ACQUSITION PAR.	AMETERS	Min Offset	28	
Bin size	20 X 20 m	Max Offset	5530	
Foldage	10X7=70	Record length	6.0 sec	
Group interval:	40 m	Sample interval	2.0 ms	
Shot Interval	40 m	Pre-amp gain	0 dB	
Geometry (Receiver &	Assy.Split.Spread	Offset Distribution:	% of traces	
Shot point arrangement)	Orthogonal	0 - 1000	11.03	
No. of receiver lines	14	1000 - 2000	27.95	
No. of channels / line:	120+40	2000 - 3000	24.99	
Total active channels:	2240	3000 - 4000	18.9	
Receiver line interval:	280 m	4000 - 5000	15.69	
Shot line interval	320 m	>5000	1.86	

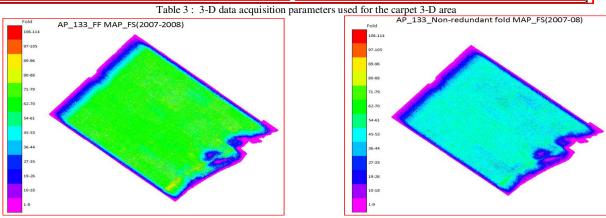


Figure 14: Full fold distribution (Left) & Non- redundant fold distribution (Right) in the 3-D area.

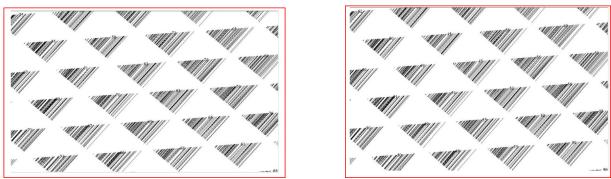


Figure 15: Offset distribution in full fold area (Left) & offset distribution in Non-redundant fold area (Right) within Bin